

**What is claimed is:**

1. A robotic cellular phone, comprising:

a plurality of wheels formed on a part of rechargeable battery;

5 a wheel driving motor for supplying power to the plurality of wheels;

an antenna driving motor for supplying power to an antenna and for moving the antenna to an optimum location;

10 a folder driving motor for supplying power for opening, closing, and rotating a folder in response to a receiving signal or a termination signal by pushing an ending button; and

a micro-processor for outputting control signals for controlling operations of the wheel driving motor, the antenna driving motor, and the folder driving motor.

2. A robotic cellular phone, comprising:

15 a vibrating motor for making a different vibration according to an emotional pattern by modeling a frequency of a vibrator based on a major or minor key harmony;

a perfume spraying device for spraying perfume through a micro-nozzle; and

20 a micro-processor for identifying a sender by comparing data between sender telephone information included a receiving signal and a telephone data stored in an internal memory and for controlling operations of the vibrating motor and the perfume spraying device.

3. A robotic cellular phone, comprising:

a photo sensor for a sensing luminosity of a surrounding device;

25 a temperature sensor for sensing temperatures of the surrounding device;

a touch sensor for sensing a touch between a human and the surrounding device;

and

a micro-processor for outputting a communication control signal in response to outputs of the photo sensor, the temperature sensor, and the touch sensor.

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4. A robotic cellular phone, comprising:

a self-environmental recognition function part for recognizing an external

environment by a photo sensor for a sensing luminosity of a surrounding device; a temperature sensor for sensing temperatures of the surrounding device; and a touch sensor for sensing a touch between a human and the surrounding device;

5 a mobility function part for moving the antenna to an optimum location to increase a sending or receiving signal sensitivity and for opening and closing a folder by using a plurality of wheels formed on a part of rechargeable battery; and

an emotion function part for identifying a sender by comparing data between sender telephone information included a receiving signal and a telephone data stored in an internal memory; and for making a different vibration according to an emotional pattern by  
10 modeling a frequency of a vibrator based on a major or minor key harmony or for spraying perfume through a micro-nozzle.

5. A robotic cellular phone of claim 4, wherein the mobility function part comprises:

a plurality of wheels formed on a part of rechargeable battery;

15 a wheel driving motor for supplying power to the plurality of wheels;

an antenna driving motor for supplying power to an antenna and for moving the antenna to an optimum location;

a folder driving motor for supplying power for opening, closing, and rotating a folder in response to a receiving signal or a termination signal by pushing an ending  
20 button; and

a micro-processor for outputting control signals for controlling operations of the wheel driving motor, the antenna driving motor, and the folder driving motor.

6. A robotic cellular phone of claim 4, wherein the emotion function part comprises:

25 a vibrating motor for making a different vibration according to an emotional pattern by modeling a frequency of a vibrator based on a major or minor key harmony;

a perfume spraying device for spraying perfume through a micro-nozzle; and

a micro-processor for identifying a sender by comparing data between sender telephone information included a receiving signal and a telephone data stored in an internal  
30 memory and for controlling operations of the vibrating motor and the perfume spraying device.

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7. A robotic cellular phone of claim 4, wherein the recognition function part comprises:

a photo sensor for a sensing luminosity of a surrounding device;

a temperature sensor for sensing temperatures of the surrounding device;

5 a touch sensor for sensing a touch between a human and the surrounding device;  
and

a micro-processor for outputting a control signal in response to outputs of the photo sensor, the temperature sensor, and the touch sensor.

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